

Selected HW #8 Answers

Palm 9.13 Using the “rule of thumb” approximations:

$$\omega_r \approx 1.4 \text{ rad/s} \quad M_r(\zeta = 0.1) \approx \frac{5}{20} \quad M_r(\zeta = 0.3) \approx \frac{1.67}{20}$$

Note the actual answers for $\zeta=0.3$ is a bit different:

$$\omega_r = 1.28 \text{ rad/s} \quad M_r(\zeta = 0.3) = \frac{1.74}{20}$$

Palm 9.14 $c > 2.6$

Palm 9.15 $k=208 \quad \frac{10}{8} \sin\left(4t - \frac{\pi}{2}\right)$

Palm 9.18 $\omega_r \approx \sqrt{600} \text{ rad/s} \quad G(\omega_n) = \frac{1}{c\sqrt{600}}$

1. $\omega_n \approx 13 \text{ Hz}$

2. a) $G(\omega) = \frac{1}{\sqrt{(20-2\omega^2)^2 + (22\omega)^2}} \quad G_{DC} = \frac{1}{20} \quad \phi(\omega) = -\tan^{-1}\left(\frac{22\omega}{20-2\omega^2}\right)$

b) $G(\omega) = \frac{1}{\sqrt{(27-3\omega^2)^2 + (4\omega)^2}} \quad G_{DC} = \frac{1}{27} \quad \phi(\omega) = -\tan^{-1}\left(\frac{4\omega}{27-3\omega^2}\right)$

c) $G(\omega) = \frac{1}{|100-4\omega^2|} \quad G_{DC} = \frac{1}{100} \quad \phi(\omega) = -\tan^{-1}\left(\frac{0}{100-4\omega^2}\right)$
 Note: $\phi(\omega < 5) = 0$
 $\phi(\omega > 5) = -180$

d) $G(\omega) = \frac{1}{\sqrt{(4\omega^2)^2 + (100\omega)^2}} \quad G_{DC} = \infty \quad \phi(\omega) = -\tan^{-1}\left(\frac{100}{-4\omega}\right)$
 Note: $\phi(0) = -90 \text{ deg}$

3.

4. $x(t) = A_1 e^{-2t} \cos(\sqrt{12}t + A_2) + \frac{3}{\sqrt{481}} \sin\left(5t - \tan^{-1}\left(\frac{20}{-9}\right)\right)$

5. a) $K_I = 0.2531$

b) $\tau = 10e + 8 \int e \, dt$

6. a) $F = [J(18)^2 - kl^2]e + [9.2J - bl^2]\dot{e}$

Palm 10.5

For small k_p , the dominant eigenvalue is approximately $s \cong -\frac{k_p+1}{5}$.

For mid k_p , the second eigenvalue has a significant impact on the dominant eigenvalue (i.e. no longer equal to value above).

For large k_p , eigenvalues are complex

Palm 10.39

$$k_p \geq \sqrt{10}$$

$$k_d \geq 40\sqrt{5} - 10$$