## **Conductance Sensing, Continued**

Consider this example:



CdS photoresistor  $\rightarrow$  a cadmium sulfide cell: its resistance decreases with increasing light intensity

Objects on the conveyer temporarily block the beam of light  $\rightarrow R_{CdS} \uparrow$ 

Put the sensor in series with R:



$$v_1 = V_{in} \frac{R_{CdS}}{R + R_{CdS}}$$

Light intensity  $\uparrow: R_{CdS} \downarrow: v_1 \downarrow$ 

Light intensity  $\downarrow$ : R<sub>CdS</sub>  $\uparrow$ : v<sub>1</sub>  $\uparrow$ 

Now consider this interface circuit:



No object in the light path:  $R_{CdS}$  low,  $V_1 < V_{ref}$ ,  $V_o$  low (logic level 0)

Object in the light path:  $R_{CdS}$  high,  $V_1 > V_{ref}$ ,  $V_o$  high (logic level 1), counter increments by one

The example above approximates conductivity sensing.

A CdS photoresistor is a semiconductor device that exhibits photoconductivity. CdS is a semiconductor material (usually n-type), and is used in one type of photovoltaic cells. Light above a certain frequency possesses enough energy to free an electron, creating an electron-hole pair to conduct electricity, thereby lowering resistance.  $R_{dark}$  can be up to several M $\Omega$ , while  $R_{light}$  can be as low as several hundred  $\Omega$ . CdS is highly toxic, a known carcinogen, and is sometimes used in yellow tattoo die.





CdS photoresistors are an older technology, and are relatively low frequency (~10s of Hz response to a change in light intensity). They are fairly low cost.

Example commercially available CdS photoresistor:



## **Resistance Sensing**

1. A single resistance sensor

Consider a resistive sensor,  $R_s$ , where  $R_s \propto measurand$ :



$$V_o = \frac{5R_s}{1000 + R_s}$$

Notice the  $V_o$  is a nonlinear function of  $R_s$ .

A plot of  $V_o$  vs.  $R_s$  is shown on the next page,

where 100  $\Omega \le R_s \le 1900 \Omega$ .

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Although the interface circuit is powered off of 5V, the output voltage only ranges from about 0.4 V to 3.3V.

Although  $R_s$  might be linearly proportional to the measurand,  $V_o$  is clearly not linearly proportional to  $R_s$ . Is this a problem? It might be or it might not be, depending on the application.

## 2. A differential resistance sensor

Here, the sensor consists of two resistors,  $R_1$  and  $R_2$ , similar to a potentiometer, where the measurand causes one resistor to increase in resistance while the other one decreases by the same amount.



$$V_o = \frac{5R_2}{R_1 + R_2}$$

Let's let:  $R_1 = R_o + \Delta R$  and  $R_2 = R_o - \Delta R$ ,

where  $R_o$  is a constant and  $\Delta R$  is a function of the measurand.

Therefore: 
$$V_o = \frac{5(R_o - \Delta R)}{R_o + \Delta R + R_o - \Delta R} = 2.5 - 2.5 \frac{\Delta R}{R_o}$$

Observe that  $V_o$  is now linear function of  $\Delta R$ .



Example: Let  $Ro = 1 \ k\Omega$  and  $0 \ \Omega \le \Delta R \le 900 \ \Omega$ 

 $V_{\rm o}$  is now linearly proportional to  $-\Delta R,$  but it only goes from about 0.25 V to 2.5 V.

Similarly, let:  $R_1 = R_o - \Delta R$  and  $R_2 = R_o + \Delta R$ , resulting in

$$V_o = \frac{5(R_o + \Delta R)}{R_o - \Delta R + R_o + \Delta R} = 2.5 + 2.5 \frac{\Delta R}{R_o}$$

yielding:

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Which is still a linear response, but the slope is now positive, with  $V_{\rm o}$  between about 2.5 V and 4.75 V.

3. Dual differential resistance sensor

Some resistance sensors consist of 4 resistors, arranged as two differential pairs:

 $R_{1} = R_{o} + \Delta R$  $R_{2} = R_{o} - \Delta R$  $R_{3} = R_{o} - \Delta R$  $R_{4} = R_{o} + \Delta R$ 

Let's connect the 4 resistors as shown below:

$$U \bigoplus R_1 \ge R_{0} + DR$$

$$= \frac{V \bigoplus V_1 + V_2 - DR}{R_1 \ge R_0 - DR}$$

$$R_1 \ge R_0 - DR$$

$$R_2 \ge R_0 - DR$$

$$R_4 \ge R_0 + DR$$

Notice that the resistors are connected to realize two differential pairs where one is inverted compared to the other one. The is called a <u>Wheatstone Bridge</u> sensor configuration.

$$V_{1} = \frac{V(R_{o} - \Delta R)}{R_{o} + \Delta R + R_{o} - \Delta R} = \frac{V(R_{o} - \Delta R)}{2R_{o}}$$
$$V_{2} = \frac{V(R_{o} + \Delta R)}{R_{o} + \Delta R + R_{o} - \Delta R} = \frac{V(R_{o} + \Delta R)}{2R_{o}}$$
Let's define:  $V_{o} = V_{2} - V_{1} = \frac{V(R_{o} + \Delta R)}{2R_{o}} - \frac{V(R_{o} - \Delta R)}{2R_{o}} = V\frac{\Delta R}{R_{o}}$ Example:  $R_{o} = 1 \text{ k}\Omega$ ,  $V = 5 \text{ V}$ ,  $0 \Omega \le \Delta R \le 900 \Omega$ 

yielding:

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 $V_o$  is a linear function of  $\Delta R$ .

Notice that this configuration has a larger  $V_o$  range (0 V to 4.5 V) than with the 2-resistor differential resistance sensor, i.e. this is a more sensitive sensor.