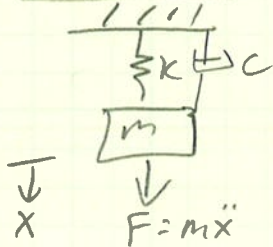


1. Inertial MEMS Devices

→ inertial forces: $m\ddot{x}$ displaces the proof mass against the suspension system restraining force

a. Accelerometer



at steady state: $kx = m\ddot{x} = ma$

let $x = \text{displacement} = d \rightarrow d = a \frac{m}{k} = aS$

$S = \text{accelerometer sensitivity}$

$$S = \frac{m}{k} = \frac{1}{\omega_n^2}, \quad [S] = s^2$$

b. Gyroscope

→ Resonating or vibrating proof mass along x -axis

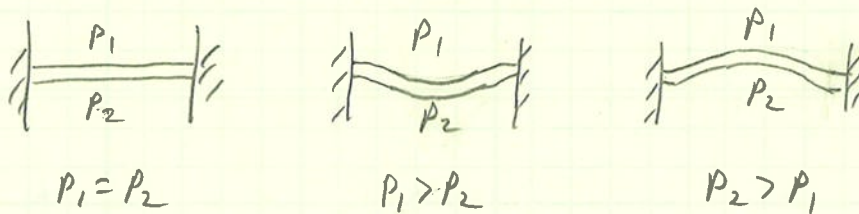
→ If rotated with angular rate, Ω , about z -axis,

sinusoidal motion occurs along y -axis due to

the Coriolis acceleration: $a_y \approx 2\Omega\dot{x}$

c. Pressure Sensor

→ very similar to an accelerometer except that the proof mass is replaced by a diaphragm or a membrane that deforms due to a difference in pressure



$$P = \text{Force/area} = F/A \rightarrow F = PA = KX, \quad \text{displacement, } X = \frac{PA}{K}$$

→ For more in-depth coverage: take ELEC 5760/6760: Solid State Sensors

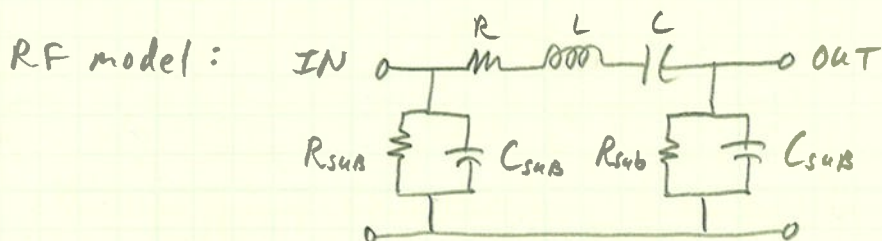
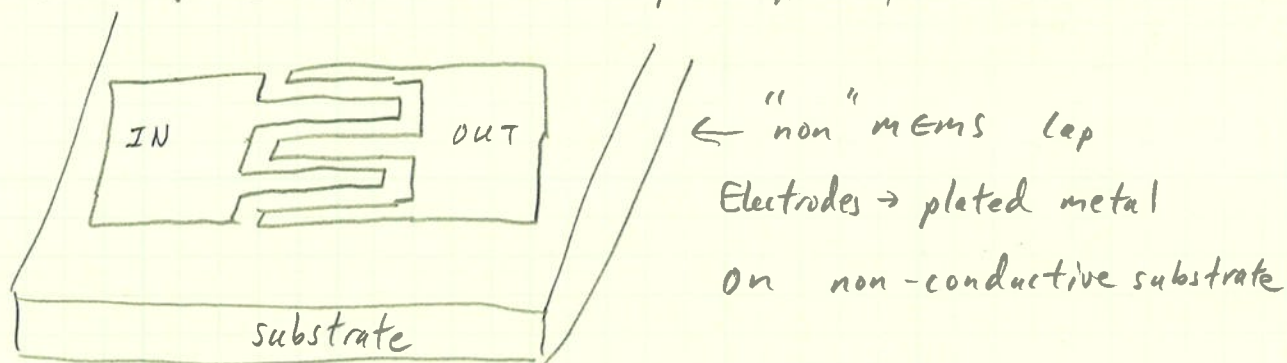
2. RF MEMS

→ MEMS Technology can enable unique RF Devices

a. Static RF MEMS Device

① RF Capacitors

i. Interdigital Capacitor : $C \leq 1\text{pF}$ typically



R_{sub}, C_{sub} → parasitics due to the substrate → limits the properties of the RF capacitor

MEMS Technology

→ remove the substrate from up under the interdigitated electrode fingers

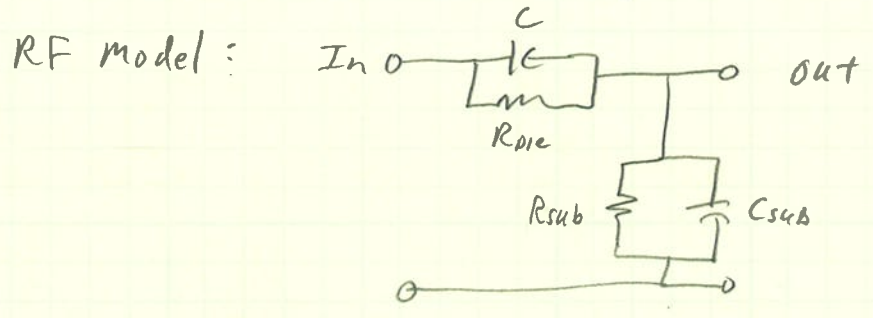
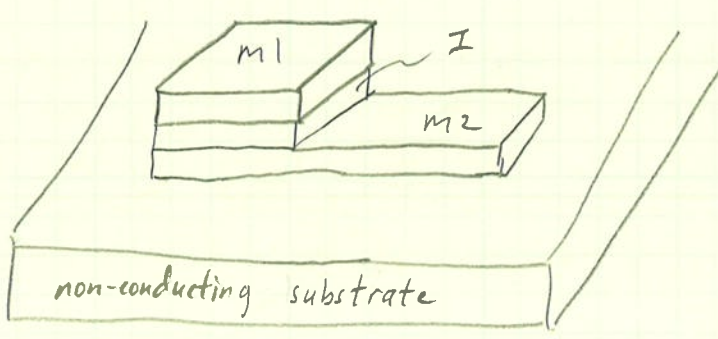
possible techniques → (1) anisotropic wet etch

(2) XeF_2 dry etch

(3) backside DRIE

→ 20% performance improvement is possible

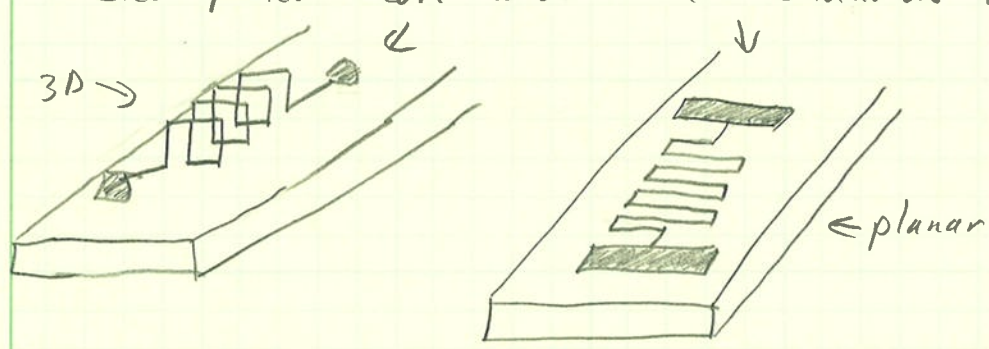
b. MIM Capacitor : $C > 1\text{pF}$ typically
↳ "metal-insulator-metal"



→ also improve by removing substrate under the cap area

② RF Inductors

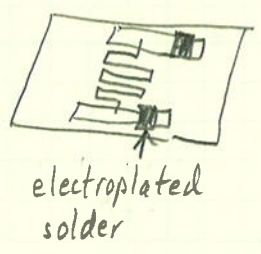
→ Electroplated Coil and Planar Inductors on non-conductive substrates



→ Improve by removing substrate from under inductor structure

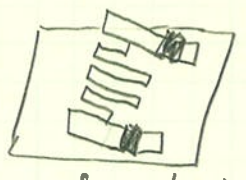
* Self Assembled Inductor

(1) Planar Fab



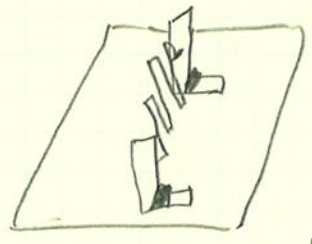
electroplated solder

(2) heat solder



surface tension stands up structure

(3) cool solder



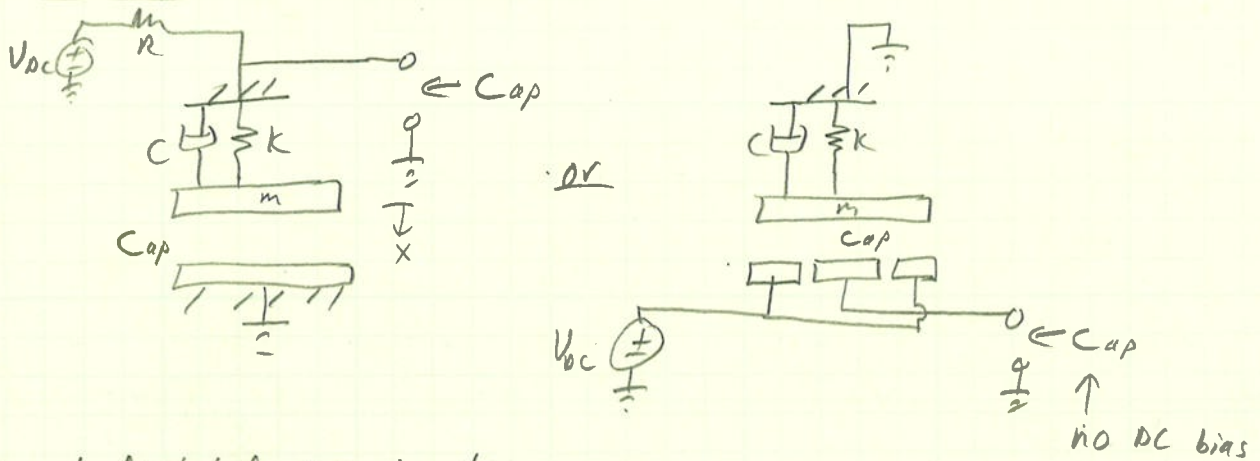
Inductor now stands up vertically off of substrate

b. Variable RF Devices → Varactors

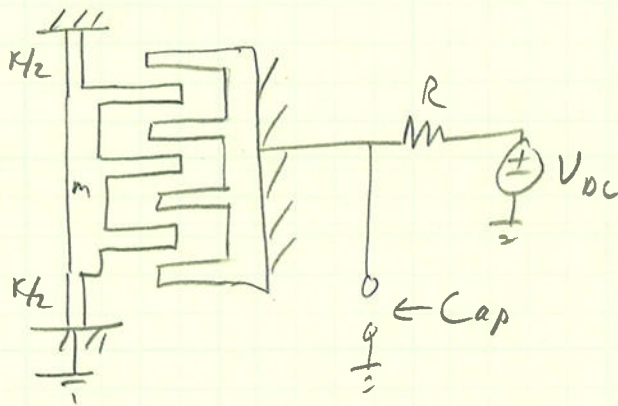
→ tunable RF Caps : usually consists of a high DC voltage variable capacitor used in low voltage RF applications

→ DC adjustment voltage does not affect RF circuit
i.e. → use DC blocking caps, etc.

① Parallel Plate RF Varactor



② Interdigitated RF Varactor



c. Other Types of RF MEMS Devices

- ① antennas : planar, 3D, tunable
- ② switches : contact, low/high capacitance → open or snapped in PPA
- ③ RF Cavity resonators
- ④ micromachined high freq mechanical resonators
- ⑤ micromachined acoustic wave devices : SAW, etc.
- ⑥ MEMS combined with RFID technology : sensors, etc.