

1) Thermal Sensing and Actuation → Chapter 5 in text book

→ materials expand when heated → thermal expansion

a. Linear Expansion Coefficient → material property

→ a relative dimensional change per unit temperature

increase :  $\alpha = \frac{\Delta L/L}{\Delta T}$  ,  $(\alpha) = \times 10^{-6}/^{\circ}\text{C}$  → Note: Book error  $\alpha$  &  $\beta$

→ also called the "Coefficient of Thermal Expansion" (CTE)

or "Thermal Expansion Coefficient" (TEC)

→ Volumetric Expansion Coefficient :  $\beta = \frac{\Delta V/V}{\Delta T} \cong 3\alpha$

Example values for CTE : Table 5.2, p. 183

Al → 25 (2.5 is error in book)

Al Oxide → 8.7

Si → 2.6

Au → 14.2

SiO<sub>2</sub> → 0.35

Ni → 13

Ti → 8.6

Differences in CTE between two attached materials results in stress, strain and sometimes mechanical failure when the temperature changes from the bonding temperature

→ often a major problem in microfabrication

ex:  $\text{CTE}_{\text{Si}}/\text{CTE}_{\text{SiO}_2} = 2.6/0.35 = 7.4$

→ Si expand or contracts 7.4 x more than SiO<sub>2</sub> for a temp increase or decrease

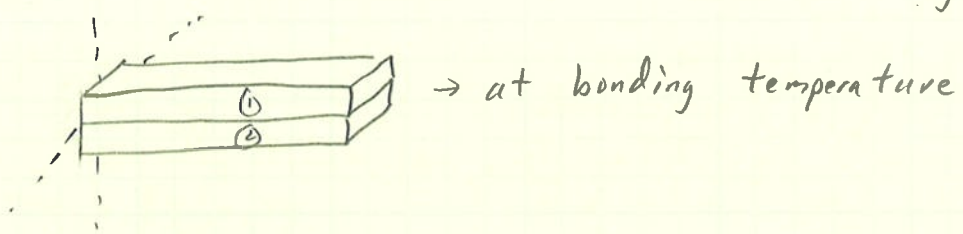
Ex: how much does a Si cantilever elongate for a 100° temperature increase? (beam is 1mm long)

$$d = L \alpha \Delta T$$

$$= (1 \times 10^{-3})(2.6 \times 10^{-6})(100) = 0.26 \mu m$$

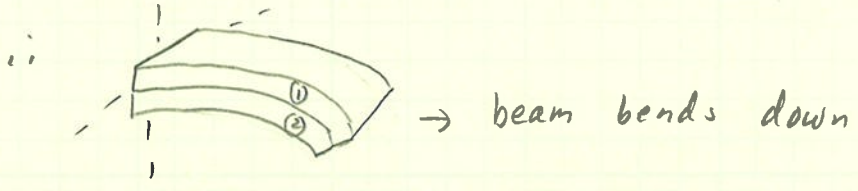
b. Thermal Bimorph

Consider a beam clamped on one end made of two materials with different CTEs, bonded longitudinally:

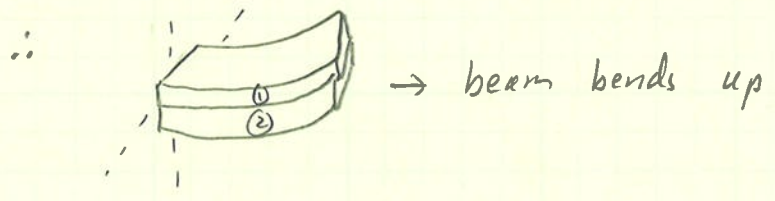


let  $CTE_{(1)} > CTE_{(2)}$

if Temperature increases: ① expands more than ②



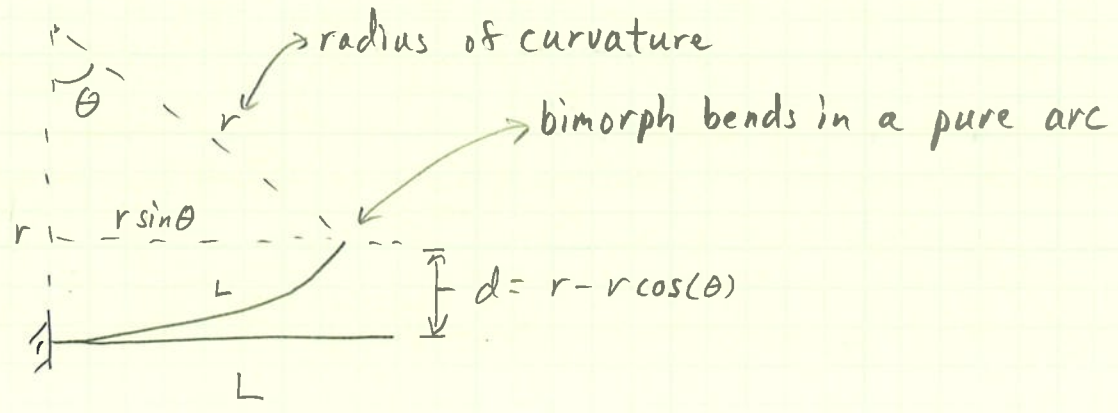
if Temperature decreases: ② contracts more than ①



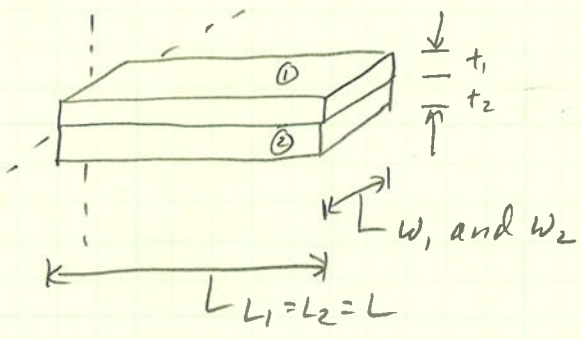
① Sensing Temperature: measure deflection or strain to determine temperature

② Actuator → add a resistive heater onto the bimorph and use Joule heating to deflect the bimorph

# 1. Mathematical modeling the Bimorph



$L = r\theta \rightarrow [\theta] = \text{rad}$



material ①  $\rightarrow \alpha_1, E_1$   
 material ②  $\rightarrow \alpha_2, E_2$

$r \equiv$  radius of curvature

$$\frac{1}{r} = \frac{6w_1w_2E_1E_2t_1t_2(t_1+t_2)(\alpha_1-\alpha_2)\Delta T}{(w_1E_1t_1^3)^2 + (w_2E_2t_2^3)^2 + 2w_1w_2E_1E_2t_1t_2(2t_1^2+3t_1t_2+2t_2^2)}$$

$\rightarrow$  Why use thermal Bimorph actuators?

$\rightarrow$  tolerant of environments PPA/CDA's will not work:

- (1) dirty (dust, etc)
- (2) in liquids (water, bio, etc)
- (3) easy to make an angular displacement based on input energy  $\rightarrow$  current  $\Rightarrow$  heat  $\Rightarrow \Delta T \Rightarrow \theta$

## 2. Thermal Sensors (covered in detail in Sensors course)

### (1) Micro Thermocouples

→ temperature dependent voltage between 2 dissimilar metals bonded at a point → Seebeck effect

### (2) Thermal Resistor

↳ conductors ⇒ resistance increases with temperature

$$R_T = R_0 (1 + \alpha_R (T - T_0))$$

$\alpha_R$  = temperature coefficient of resistance

### (3) Thermistor

→ semiconductor temperature dependent device

$$R = R_0 e^{[B(1/T - 1/T_{ref})]}$$

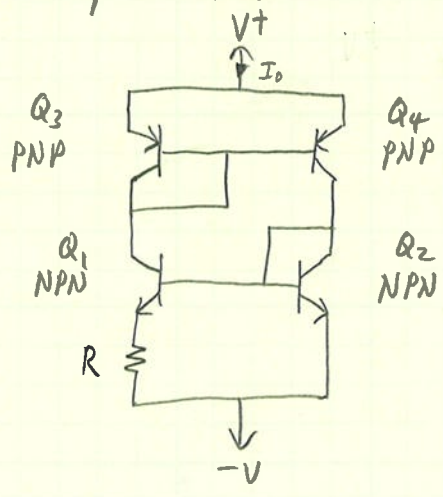
→ response is nonlinear with temperature

→ low cost → used for medical thermometers

### (4) Thermodiodes, Thermotransistors and the PTAT

→ temperature dependent current (also fabrication dependence)

→ PTAT → "Proportional To Absolute Temperature"



$$I_0 \approx \frac{2k_B T}{q R} \ln\left(\frac{A_{E2}}{A_{E1}}\right)$$

→ removes fab. tol. dependence

→ often used in MEMS device in order to calibrate out temperature effects → most MEMS devices. (i.e. sensors) are sensitive to temp. changes

