

## 6 Force Analysis

### Homework 11: Joint reaction forces and equilibrium moment

#### Problem 6.3

The mechanism in Fig. P6.3 has the dimensions:  $AB=200$  mm,  $AC=600$  mm,  $BD=1000$  mm,  $L_a=150$  mm,  $L_b=250$  mm, and  $EF=600$  mm. The driver link 1 rotates with a constant angular speed of  $n=60$  rpm.

The links are homogeneous rectangular prisms made of steel with the width  $h = 0.01$  m and the depth  $d = 0.001$  m. The steel sliders 3 and 4 have the width  $w_{Slider} = 0.05$  m, the height  $h_{Slider} = 0.02$  m, and the depth  $d = 0.001$  m. The density of the material is  $\rho_{Steel} = 8000$  kg/m<sup>3</sup> and the gravitational acceleration is  $g = 9.807$  m/s<sup>2</sup>.

The external moment on 5 is opposed to the motion of the link

$$\mathbf{M}_{ext} = \mathbf{M}_{5ext} = -|\mathbf{M}_{ext}| \frac{\boldsymbol{\omega}_5}{|\boldsymbol{\omega}_5|}, \text{ where } |\mathbf{M}_{ext}| = 900 \text{ N}\cdot\text{m}.$$

Find the equilibrium moment on link  $AB$  and the joint reaction forces for  $\phi=\phi_1=120^\circ$ .

For  $\phi=120^\circ$  the kinematics of the mechanism are given by:

$$\begin{aligned} x_B &= -0.1 \text{ m}, & y_B &= 0.173205 \text{ m}, \\ x_C &= -0.6 \text{ m}, & y_C &= 0 \text{ m}, \\ x_D &= -1.04491 \text{ m}, & y_D &= -0.154122 \text{ m}, \\ \phi_2 &= 0.333473 \text{ rad}, & \phi_5 &= -0.940376 \text{ rad}, \\ \dot{x}_{B_1} &= -1.08828 \text{ m/s}, & \dot{y}_{B_1} &= -0.628319 \text{ m/s}, \\ \ddot{x}_{B_1} &= 3.94784 \text{ m/s}^2, & \ddot{y}_{B_1} &= -6.83786 \text{ m/s}^2, \\ v_{C_2C_3} &= -1.23399 \text{ m/s}, & \omega_2 &= -0.448799 \text{ rad/s}, \\ \dot{x}_{D_2} &= -1.23518 \text{ m/s}, & \dot{y}_{D_2} &= -0.204243 \text{ m/s}, \\ a_{C_2C_3x}^{cor} &= -0.362557 \text{ m/s}^2, & a_{C_2C_3y}^{cor} &= 1.04661 \text{ m/s}^2, \\ a_{C_2C_3} &= 1.59873 \text{ m/s}^2, & \alpha_3 &= -16.7458 \text{ rad/s}^2, \\ \ddot{x}_{D_2} &= -1.34318 \text{ m/s}^2, & \ddot{y}_{D_2} &= 9.05135 \text{ m/s}^2, \\ v_{D_5D_4} &= 0.893105 \text{ m/s}, & \omega_5 &= -1.75371 \text{ rad/s}, \\ a_{D_5D_4x}^{cor} &= 2.53037 \text{ m/s}^2, & a_{D_5D_4y}^{cor} &= -1.84656 \text{ m/s}^2, \\ a_{D_5D_4} &= -4.98108 \text{ m/s}^2, & \alpha_5 &= -6.57248 \text{ rad/s}^2. \end{aligned}$$

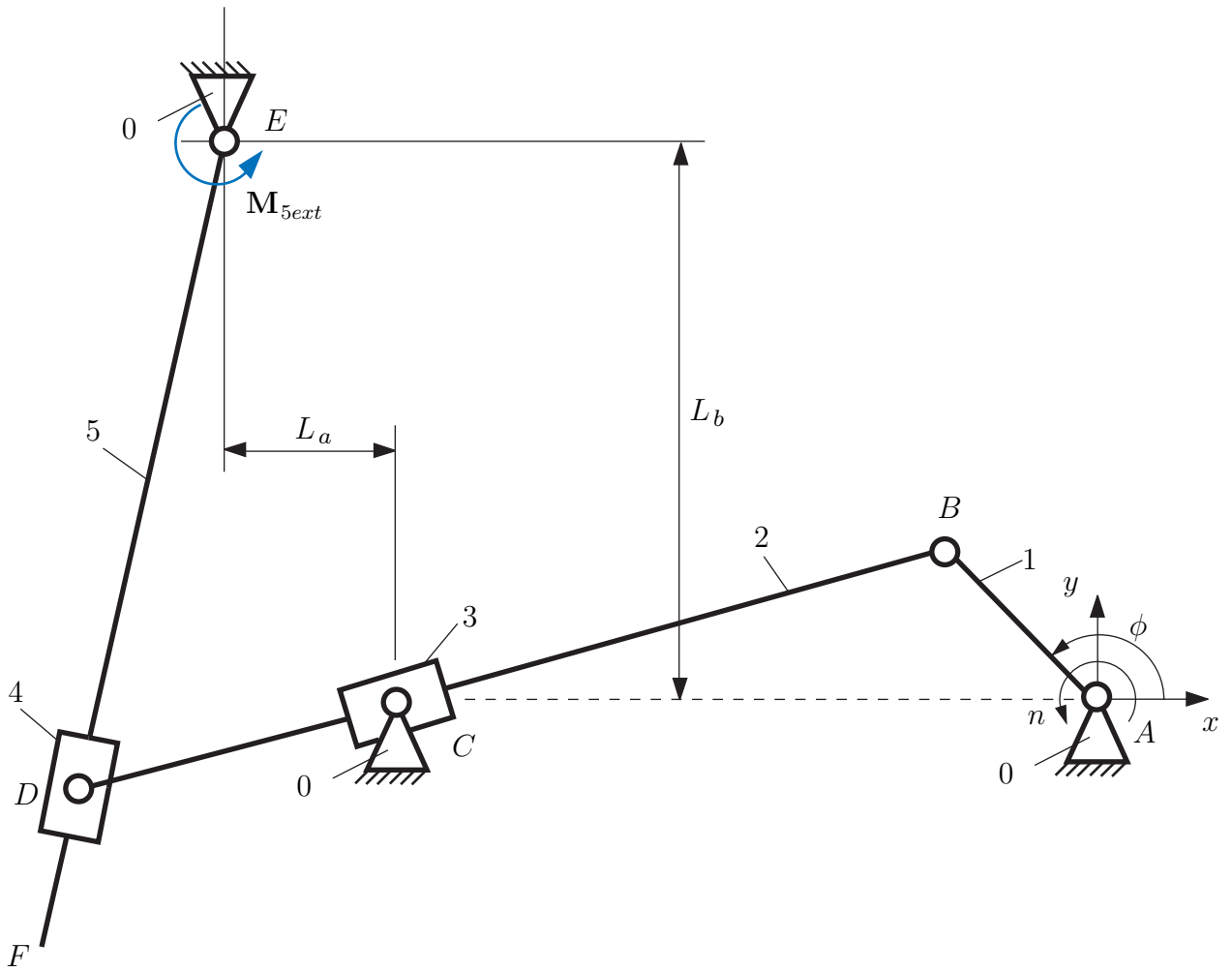


Figure P6.3

**Problem 6.6**

The dimensions of the mechanism shown in Fig. P6.6 are:  $AB=180$  mm,  $AC=90$  mm,  $CD=200$  mm,  $CF = CD$ , and  $AG = CD + AC$ . The constant angular speed of the driver link 1 is  $n=180$  rpm. The links are homogeneous rectangular prisms made of steel with the width  $h = 0.01$  m and the depth  $d = 0.001$  m. The sliders 2 and 4 have the width  $w_{slider} = 0.05$  m, the height  $h_{slider} = 0.02$  m, and the depth  $d = 0.001$  m. The density of the material is  $\rho_{Steel} = 8000$  kg/m<sup>3</sup> and the gravitational acceleration is  $g = 9.807$  m/s<sup>2</sup>.

The external moment on 5 is opposed to the motion of the link

$$\mathbf{M}_{ext} = \mathbf{M}_{5ext} = -|\mathbf{M}_{ext}| \frac{\boldsymbol{\omega}_5}{|\boldsymbol{\omega}_5|}, \text{ where } |\mathbf{M}_{ext}| = 1500 \text{ N}\cdot\text{m}.$$

Find the equilibrium moment on link  $AB$  and the joint reaction forces for  $\phi=\phi_1=60^\circ$ .

For  $\phi=60^\circ$  the kinematics of the mechanism are given by:

$$\begin{aligned} x_B &= 0.09 \text{ m}, y_B = 0.155885 \text{ m}, \\ x_D &= -0.16138 \text{ m}, y_D = -0.0281381 \text{ m}, \\ \phi_2 &= 0.631914 \text{ rad}, \phi_4 = 0.172624 \text{ rad}, \\ \dot{x}_{B_1} &= -2.93835 \text{ m/s}, \dot{y}_{B_1} = 1.69646 \text{ m/s}, \\ \ddot{x}_{B_1} &= -31.9775 \text{ m/s}^2, \ddot{y}_{B_1} = -55.3867 \text{ m/s}^2, \\ \dot{x}_{D_3} &= 3.28823 \text{ m/s}, \dot{y}_{D_3} = -4.4918 \text{ m/s}, \\ \ddot{x}_{D_3} &= 178.405 \text{ m/s}^2, \ddot{y}_{D_3} = 18.6037 \text{ m/s}^2, \\ \omega_2 = \dot{\phi}_2 &= 27.8338 \text{ rad/s}, \alpha_2 = \ddot{\phi}_2 = 451.854 \text{ rad/s}^2, \\ \omega_4 = \dot{\phi}_3 &= 30.4604 \text{ rad/s}, \alpha_4 = \ddot{\phi}_3 = 992.942 \text{ rad/s}^2. \end{aligned}$$

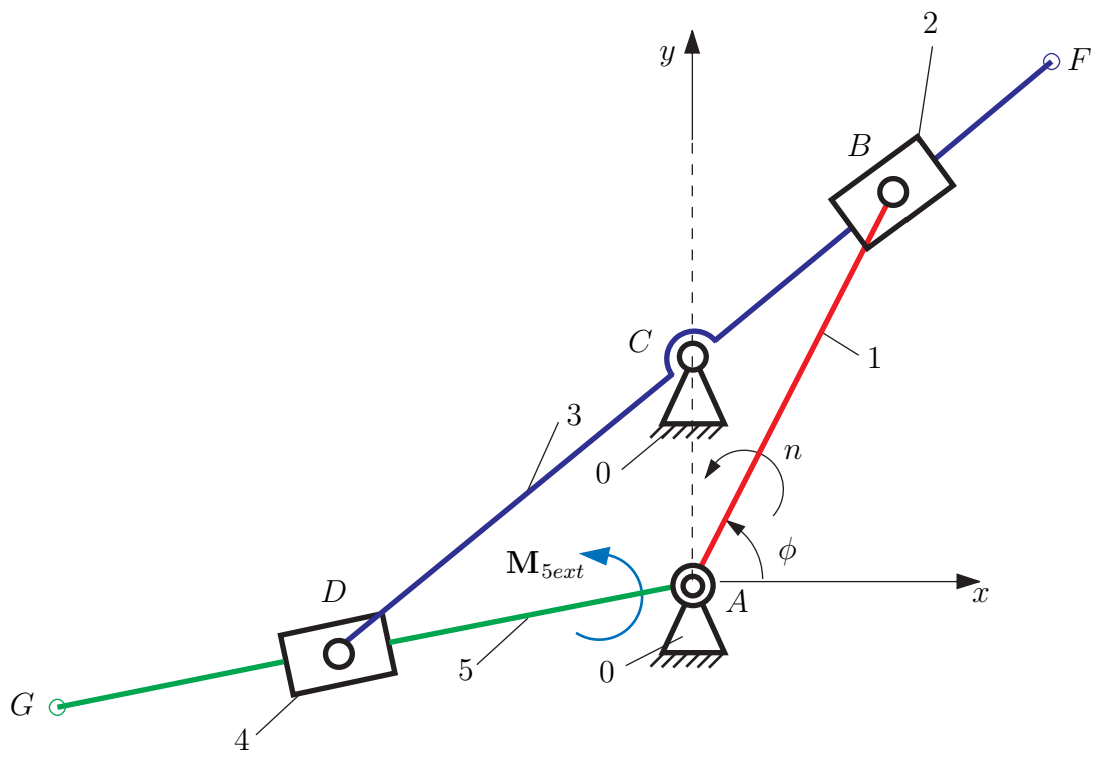


Figure P6.6