

NOVEL INDUCTORLESS NEURISTOR LINE

Indexing terms: Delays, Neural nets

A novel inductorless neuristor line having the desired properties of the axon is described. Each section of the line consists of a pair of *p-n-p-n-p-n* transistors and an *RC* circuit with small capacitor values. This allows integration of the line using semiconductor technology.

There are great difficulties in the integration of known neuristor line models because of the necessity of using large capacitances of the order of several thousands of picofarads^{1, 2, 7} or the necessity of inductances.^{4, 5, 9} Moreover, most of the proposed models^{2, 4, 6-8} do not exhibit all of the following desired properties of the axon:

- (a) constant pulse-propagation velocity
- (b) threshold point (if pulse height exceeds it, pulse propagation is possible, if not, the pulses are attenuated)
- (c) the pulse-shaping action during its propagation through the line
- (d) refractory period
- (e) annihilation of pulses in the case of their collision.

The proposed neuristor line model is based on the lumped delay line of the 'thyristor-*RC*' type shown in Fig. 1*a*. In a steady state, transistors *T*₁ and *T*₂, which form a 'thyristor' subcircuit, are cutoff, since the capacitors *C*₁ and *C*₂ are charged up to the supply voltage *V*_b. Application of a negative pulse, with respect to *V*_b, to the input port turns the transistors *T*₁ and *T*₂ into their active regions of operation and then causes saturation of *T*₂. The saturation time for *T*₂, which determines the output pulsewidth, is determined by the discharge time of the capacitor *C*₁ through the resistance *R*₃ in parallel with the nonlinear input resistance of *T*₂ and the storage time of transistor *T*₂. The charging time of *C*₁ through resistance *R*₄, after the cutoff of *T*₁, assures the existence of a refractory period in the line. Delay of the transmitted pulse

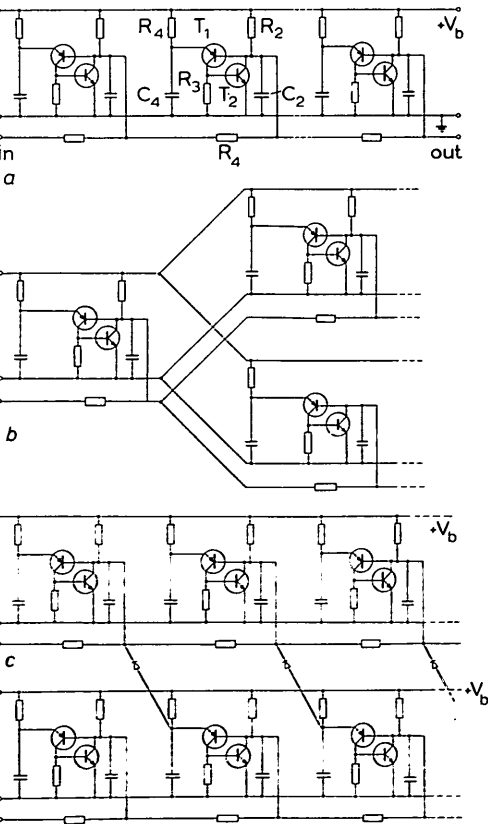


Fig. 1 Proposed inductorless neuristor line
a Schematic. *R*₁ = 10 kΩ, *R*₂ = 5.6 kΩ, *R*₃ ≈ 3 kΩ, *R*₄ = 30 kΩ, *C*₁ = *C*₂ = 50 pF
b Type-T junction realisation
c Type-R junction realisation

is achieved by the integrating circuits formed by *R*₁ and *C*₂, which are connected between active sections of the line.

Constant pulse-propagation velocity: Constant pulse-propagation velocity in the line is caused by the delay time *t*₁ of the input pulse, which is applied through the integrating circuit *R*₁ *C*₁ to each active section of the line. The delay time *t*₁ is determined by the relationship

t_1 = - (R_1 C_2 / a) ln [1 - (V_BE1 / V_in)] (1)

where *V*_{BE1} is the minimum base-emitter voltage on transistor *T*₁ which is necessary for saturation of *T*₂, *V*_{in} is the amplitude of the input pulse with respect to *V*_b and *a* = *R*₁/*R*₂ + 2.

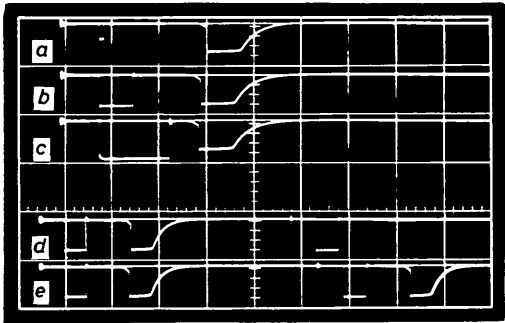


Fig. 2 Experimental results
The first pulse is an input pulse and the second pulse is an output one-on-four section
a, b, c: The pulse-shaping action. Horizontal scale is 0.3 μs/division, vertical scale is 15 V/division
d Pulse period smaller than the refractory time
e Pulse period greater than the refractory time
d and e Horizontal scale is 0.5 μs/division, vertical scale is 15 V/division

Threshold point: To initiate the regeneration process in each active section it is necessary to apply a negative input pulse having the amplitude greater than *V*_p:

V_in ≥ V_p = a V_BE1 (2)

The duration of the input pulse with this amplitude should be large enough to allow transistor *T*₁ to turn on into its active region, usually greater than *t*₁.

Pulse-shaping action: The shaping of the propagated pulse through the line depends on the time constant *R*_{BE2} || *R*₃/*C*₁ and on the storage time *τ* of the transistor *T*₂. The propagated pulse duration time *t*₂,

t_2 = [R_BE2 || R_3] C_1 ln [(V_b / V_BE2)] + τ (3)

is determined by the first component of eqn. 3, i.e. by the time after which the voltage between the base and emitter of *T*₂ becomes smaller than the voltage *V*_{BE2} determining the cutoff state of *T*₂. In a practically realised circuit, the storage time *τ* was negligible. The output pulse amplitude is approximately equal to the supply voltage *V*_b.

Refractory period: The refractory period of the line is caused by the existence of the cutoff base-emitter voltage at the transistor *T*₁ after passing of the pulse through each section of the line. The refractory time *t*₃ is expressed in terms of the charging time of *C*₁ and the propagated pulse-duration time *t*₂:

t_3 = R_4 C_1 ln [(V_b - V_BE2) / ((V_in/a) - V_BE1)] + t_2 (4)

Annihilation of pulses: Annihilation of pulses in the case of their collision when pulses are propagating from opposite directions is a consequence of the existence of the refractory period, which causes pulse attenuation. The practical importance of proposed neuristor line models depends on simple realisations of T-type and R-type junctions.³ These are shown in Figs. 1*b* and *c*, respectively, for this line. These junctions

allow realisation of neuristor logic elements^{3, 10} used for simulated neural networks. The experimental results for the discussed neuristor line are shown in Figs. 2a-e. The conclusion is that the proposed line model has all the desired properties of the axon necessary for simulation of complex neural networks. The capacitances used in the practical model for $t_1 = 0.05$, $t_2 = 0.025$ and $t_3 = 3 \mu s$ are smaller than 50 pF. This allows for full integration using monolithic semiconductor technology. Additionally, the $p-n-p$ transistor T_1 may have small current gain, allowing the use of lateral transistors in a practical integrated realisation. In the resting state of the line, when all transistors are cut off, no power is consumed from the supply battery.

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ERRATUM

SHARON, T. M., MARADUDIN, A. A., and CUNNINGHAM, S. L.: 'Rectangular-ridge vibrational modes', *Electron. Lett.*, 1974, **10**, pp. 229-230

It has been kindly pointed out by P. E. Lagasse that in Fig. 2 the lowest flexural mode spectra for the infinite plate (Lamb wave) and the finite ridge of $H/W = 3$ are incorrectly drawn, owing to an erroneous interpretation of Fig. 3 of Reference 2. To correct these two mode spectra, qd should be multiplied by Ω_R/Ω for the value of Ω/Ω_R corresponding to the particular qd . Fig. 2 is shown correctly below.

The agreement between our theoretical results for a semi-infinite ridge and those for the infinite plate (as well as the experimentally determined result for the finite ridge) is better than previously indicated, especially for $qd \geq 1$. However, although closer now to the semi-infinite-ridge mode, the lowest flexural mode for the ridge with a substrate still lies above that for the infinite plate. Therefore our original conclusion concerning the cantilever aspect of finite ridges of this height/width ratio is still valid

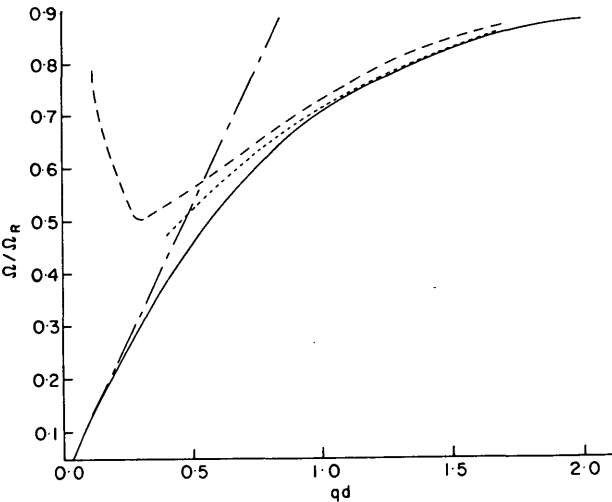


Fig. 2 Ratio Ω/Ω_R as function of qd for lowest a.s.f. mode of Duralumin 17S ridge
Broken line is experimental result for height/width ratio of 3;² solid line is theoretical result of this work; dotted line is lowest flexural mode of an infinite plate² (Lamb wave); broken-dotted line is result from thin-plate theory for flexural wave propagating along the free edge of a semi-infinite ridge⁹