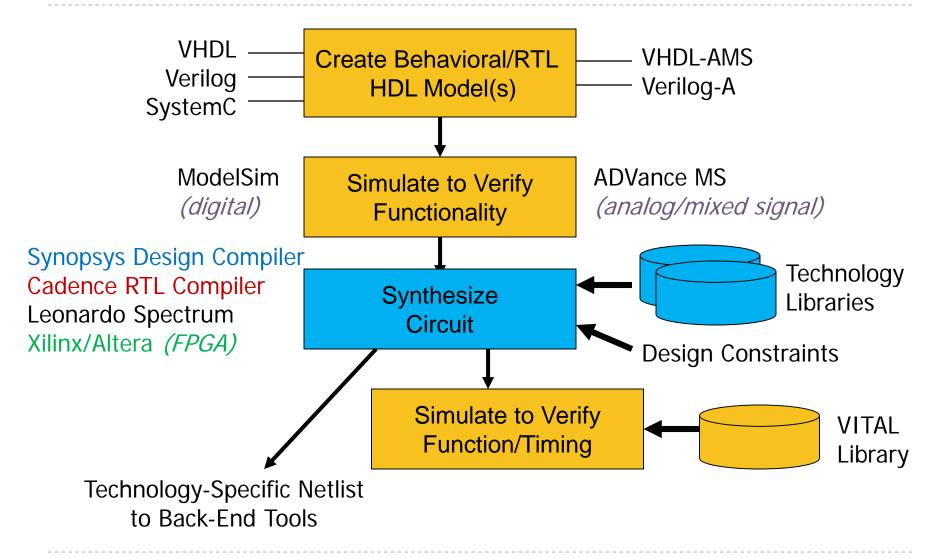
Automated Synthesis from HDL models

Design Compiler (Synopsys)

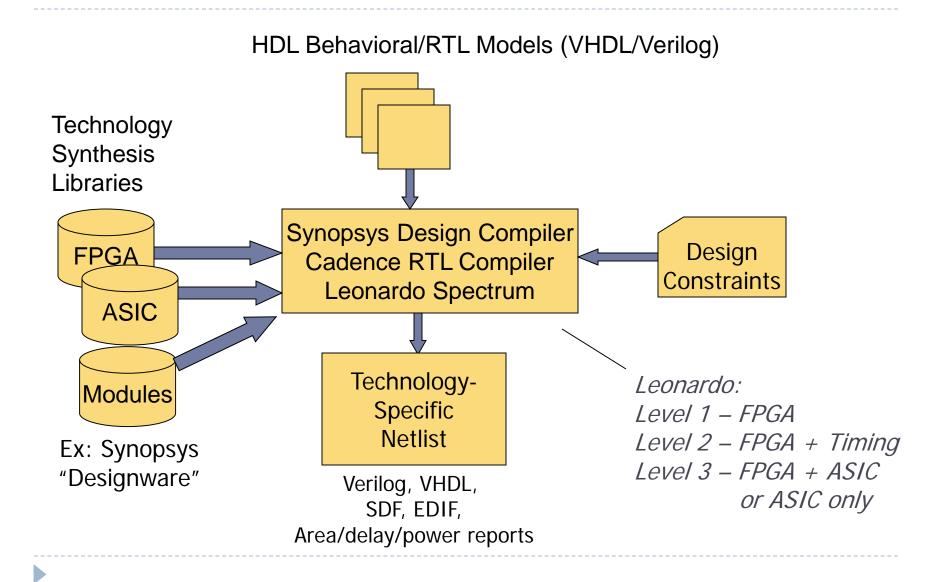
Leonardo (Mentor Graphics)

Front-End Design & Verification





Automated synthesis



Synopsys Design Compiler Documents

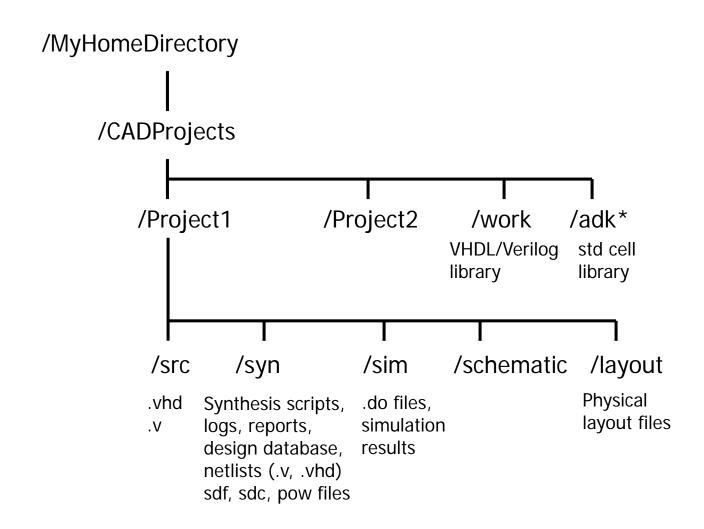
Documents (pdf) located on Linux server in

/class/ELEC6250/Synopsys_Docs/

- DC User Guide
- DC Command Line
- DC Synthesis Quickref
- DC Ref Constraints and Timing
- DC Ref Timing Optimization
- DesignVision Tutorial
- DesignVision User Guide



Project directory structure

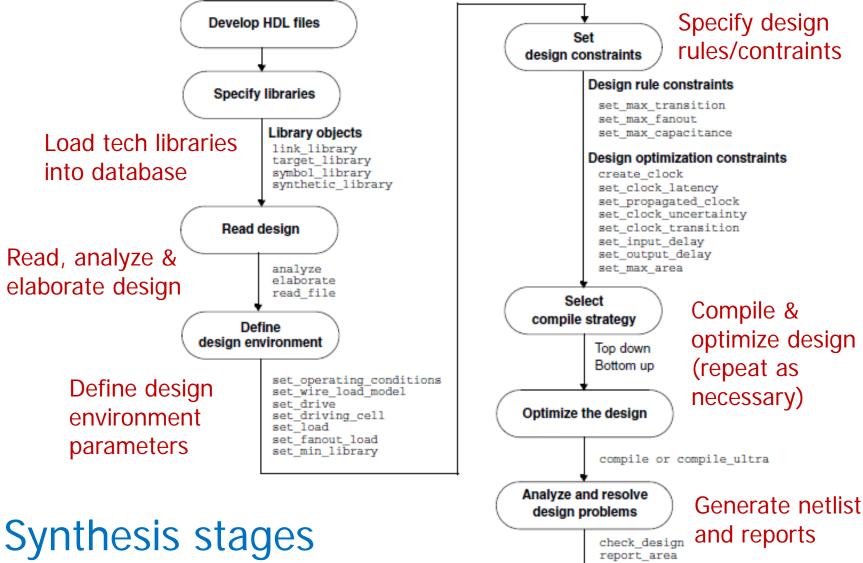




Invoking Design Compiler

- Interactive shell version:
 - dc_shell —f scriptFile
 - Most efficient and common usage is to put TCL commands into scriptFile, including "quit" at the end
 - ▶ TCL = Tool Command Language
 - ▶ Edit and rerun scriptFile as needed
- GUI version (Design Vision)
 - design_vision
 - From dc_shell: gui_start
 - Main advantage over dc_shell is to view the synthesized schematic





and commands

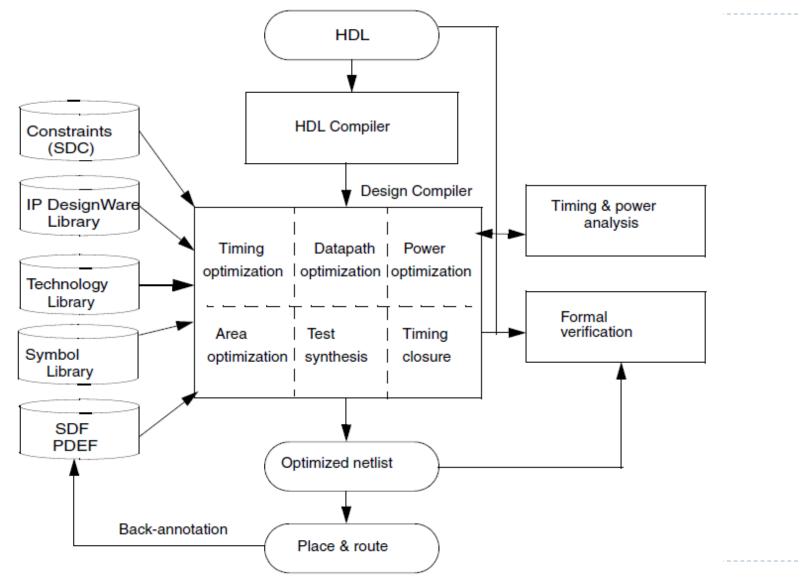
write

Save the design database

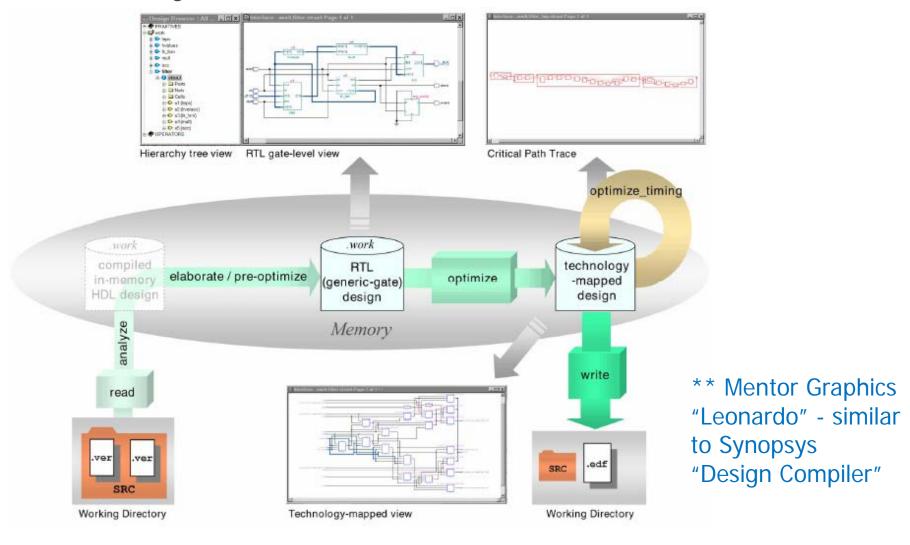
report constraint

report timing

Synopsys Design Compiler flow



ASIC synthesis flow**



- target_library : standard cell database (binary)
 - cell area/pins/timing data (for synthesis decisions)
- synthetic_library: Synopsys DesignWare components
- link_library : use during linking
 - Includes target and link library plus internal data (*)
- symbol_library : schematic symbols
 - Synopsys installation includes a generic symbol library
- Define in file .synopsys_dc.setup



Setup file (8HP): .synopsys_dc.setup

DC reads .synopsys_dc.setup files in order:

- 1. Synopsys installation directory (all user projects)
- 2. User home directory (all projects for this user)
- 3. Current project directory (this project only)

```
set MyHome [getenv "HOME"]
set SynopsysInstall [getenv "STROOT"]
set CMOS8HP "/class/ELEC6250/cmos8hp/std_cell/v.20130404"
set search_path [list |
  [format "%s%s" $CMOS8HP /synopsys/typ_v150_t025] \
  [format "%s%s" $CMOS8HP /symbols/synopsys] \
  [format "%s%s" $SynopsysInstall /libraries/syn] \
  [format "%s%s" $SynopsysInstall /dw/sim_ver] \
  [format "%s%s" $SynopsysInstall /dw]]
set target_library [list PnomV1p50T025_STD_CELL_8HP_12T.db]
set synthetic_library [list dw_foundation.sldb]
set link_library [list "*" $target_library $synthetic_library]
set symbol_library [list generic.sdb]
```

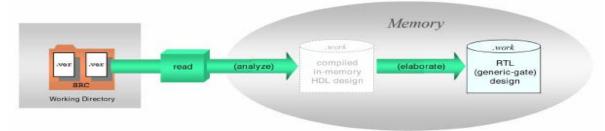
Synopsys DesignWare Package

- Predesigned components (tech-independent)
 - arithmetic, filters, CRC gen's, counters, decoders, FIFOs, flipflop RAMs, etc.
- Let DC choose a component, or instantiate directly
 - components chosen to implement arithmetic operators
- Example DW decrementer:

```
module decrementer (in_A, SUM_out);
  parameter width = 8;
  input [width-1:0] in_A;
  output [width-1:0] SUM_out;
   DW01_dec #(width) U1( .A(in_A), .SUM(SUM_out));
  endmodule;
```



- Analyze syntax check and build database
 - ▶ input VHDL and/or Verilog models
 - check dependencies & resolve generics/parameters
- ▶ Elaborate synthesize to generic gates and black boxes
 - technology-independent gates
 - operators (arithmetic, relational, etc.) recognized and implemented with "black boxes" (no logic in them yet)



Read command does analyze + elaborate + pre-optimize



Analyze Command

- analyze {fl.v src/f2.v "top file.v"}
 - Read and analyze into default memory database library "work"
 - ▶ List HDL files in <u>bottom-up</u> order <u>top level last</u>
 - Use quotes if embedded spaces in file name: "top file.v"
 - Include directory if necessary: src/f2.v
 - Analyze command switches:
 - -format verilog (or vhdl) [defaultVHDL if file ext = .vhd/.vhdl or Verilog if file ext = .v/.verilog]
 - -work lib_name [lib where design to be stored (default = "work".)
 Different libraries might be used for comparing designs]
 - Examples:
 - analyze {src/f1.v src/f2.vhd} (store in "work")
 - analyze {src/f1.v src/f2.vhd} -work lib_version2



Elaborate Command

- "Elaborate" a design currently in the memory database producing tech-independent circuit
 - elaborate divider ["divider" = VHDL entity/Verilog module]
 - Switches
 - -single_level [only do top level for bottom-up design]
 - -architecture a l [if other than most recently analyzed]
 - -work lib_name [if name other than work]
 - -generics { size=9 use_this=TRUE initval="10011" }
 - □ List format is { generic=value generic=value }
 - -parameters [format same as generics]



Example script

#Design-specific information — create variables for use in commands

```
set myFiles [list ./src/top.v ./src/Muxbig.v ]
set basename TOP
set fileFormat verilog
define_design_lib WORK —path ./syn
```

Unique for each design - not necessary, but convenient for multiple projects

#Design-independent: these commands need not be changed

```
analyze —format $fileFormat -lib WORK $myFiles
elaborate $basename —lib WORK —update
current_design $basename
link (link all design parts)
uniquify (make unique copies of replicated modules)
```

Commands using above design information



Read command

- Performs <u>both</u> analyze and elaborate steps
- Useful for single HDL file:

```
read_file —f verilog filename.v
```

Same switches as analyze and elaborate commands, plus (optional):

```
-dont_elaborate {fl.vhd} - do analysis but not elaborate
```



Design environment

- Technology variables affect delay calculations
 - Manufacturing process, temperature, voltage, fanouts, loads, drives, wireload models
- Defaults specified in the technology library
 - ▶ 8HP technology libraries on next slide
- Design environment variables can be set
 - Use tech library defaults if variables not set
 - set voltage 2.5 (volts)
 - set temp 40 (degrees celsius/centigrade)
 - set process I (process variation # if available)



Available 8HP technology files

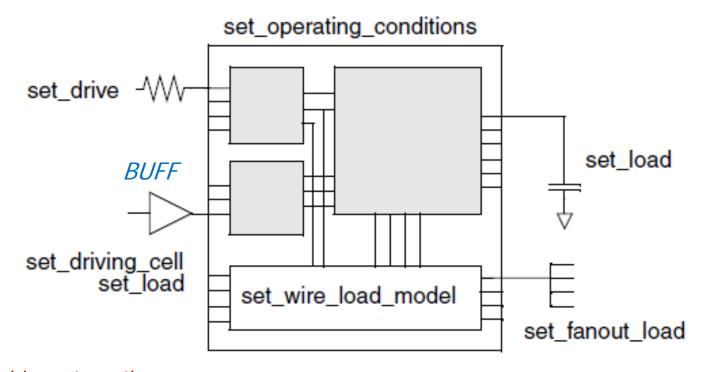
- Located in: \$CMOS8HP/synopsys/
- Each file contains data for each library cell for a specific operating voltage and temperature

Directory / Technology File

```
typ_v120_t025 / PnomV1p20T025_STD_CELL_8HP_12T.db
typ_v150_t025 / PnomV1p50T025_STD_CELL_8HP_12T.db
fast_v132_tm40 / PbcV1p32Tm40_STD_CELL_8HP_12T.db
fast_v132_tm55 / PbcV1p32Tm55_STD_CELL_8HP_12T.db
fast_v160_tm40 / PbcV1p60Tm40_STD_CELL_8HP_12T.db
fast_v160_tm55 / PbcV1p60Tm55_STD_CELL_8HP_12T.db
slow_v108_t125 / PwcV1p08T125_STD_CELL_8HP_12T.db
slow_v140_t125 / PwcV1p40T125_STD_CELL_8HP_12T.db
```



Design environment variables/commands



"drive" strength = 1/R of output driver (default 0)

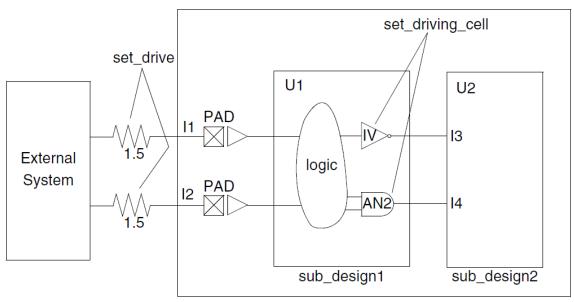
Transition delay= Rdriver*Cinput "load" = capacitive load (units from tech library) (default 0)

"fanout_load" = #units (associated with input pins)



Example: define drive characteristics





- current_design top_level_design
- set_drive 1.5 {I1 I2}
- current_cell sub_design2
- set_driving_cell -lib_cell IV {I3}
- set_driving_cell -lib_cell AN2 -pin Z -from_pin B {14}
- set_fanout_load 4 {out1 out2}

(define external input drives)

(resistance units from library)

(define input drivers for U2)

(default pin = IV output)

(arc from AN2 gate input B to output Z)

(#fanout units for output pins)



Wire Load Table (not available for 8HP)

- Estimate effects of wire length & fanout on resistance,
 capacitance and area of net
 - Affects switching times/delays
 - Precise delays known only after place and route
 - Function of cell sizes, fanouts, wire characteristics
- Wire Load Table may be provided by vendor
 - Determined from analysis of previous process runs
- Variables:
 - wire_load_library name (lib to which designed mapped - or NIL)
 - wire_table name (if named table loaded)
 - wire_tree (best,balanced,worst, or not set)
 - wire_load_mode (top, segmented)



Setting design constraints

- Design rule constraints: rules from library vendor for proper functioning of the fabricated circuit
 - Must not be violated
 - ▶ Common constraints: transition time, fanout load, capacitance
- Design optimization constraints: user-specified timing and area optimization goals
 - DC tries to optimize these without violating design rules
 - ► Common constraints: timing and area



Design rule constraints

- max_fanout = max #loads a net can drive
- Input pins have fanout_load attribute.

(load they place on driving nets)

Output pins have max_fanout attribute.

(max load they can drive)

Example: Pin N drives loads A and B

- Pin A has fanout load value 2.0
- Pin B has fanout_load value 3.0
- Pin N requires max_fanout ≥ 5.0 to drive A and B
 Otherwise, use different cell or insert a buffer to drive the net.

N

- Change max_fanout attribute to restrict it more than its default value
 set_max_fanout 5 [object_list] (object_list is list of ports)
- Other design rule constraints:
 - max_transition (output pins): transition time to change logic values
 - max_capacitance (output pins): sum of net and pin capacitances driven by output



Design optimization constraints

Speed

- path delays (min,max)
- clock specifications (period/frequency/duty)

Area

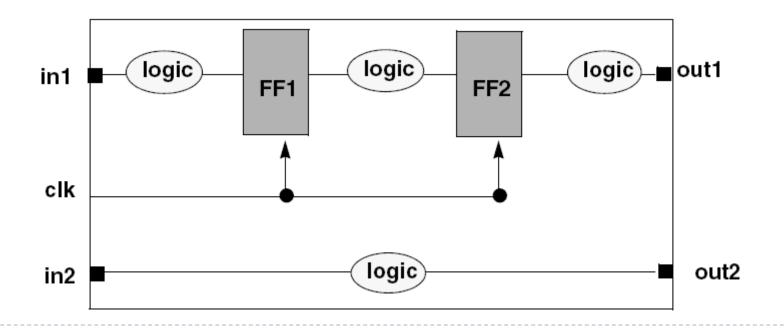
- speed is primary goal
- optimize area if timing constraints met
- target area 0 forces small as possible
- set_max_area 2000
- Choose realistic constraints (within 1-10%)
 - avoid extra buffers/gates on loaded nets



Timing path types

Path delays of interest

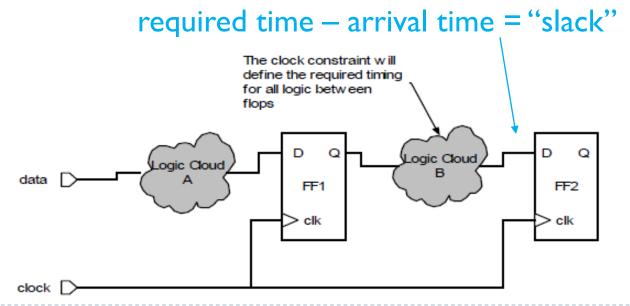
- Combinational: primary input to primary output (in2 -> out2)
- 2. Primary input to register input (in1 -> FF1/D1)
- Clock/register output to primary output (clk -> Q2 -> out1)
- 4. Clock/register output to register input (clk -> Q1 -> D2)





Timing Constraints

- Simple: specify target clock frequency
- Advanced: specify globally or on specific blocks
 - Clock: period/frequency, pulse width, duty cycle
 - Input: arrival time, transition times, driver strength
 - Dutput: required time, transition times



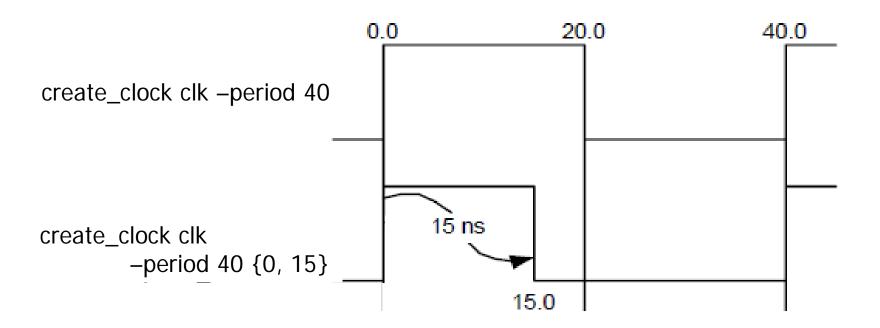


Clock specifications

- Define required period/waveform for each clock
 - create_clock ckname —period 5
 - create_clock ckname -period 5 -waveform {2 4}
 - ▶ period=5, rise at 2, fall at 4
- DC does not automatically imply clock signals
 - create_clock -name ckname -period 5
 - creates a "virtual clock" associated with a port/pin
- Clock latency = delay through clock network
 - set_clock_latency 2.1 -rise CLK1
 - set_clock_latency 0.7 -source CLK I
 - from clock origin to clock pin
- Clock uncertainty = margin of error to allow variances
 - set_clock_uncertainty -setup 0.2 CLK I
 - set_clock_uncertainty —hold 0.2 CLK I

Add 0.2 margin on either side of clock edge to account for variances in clock network

Clock constraint examples





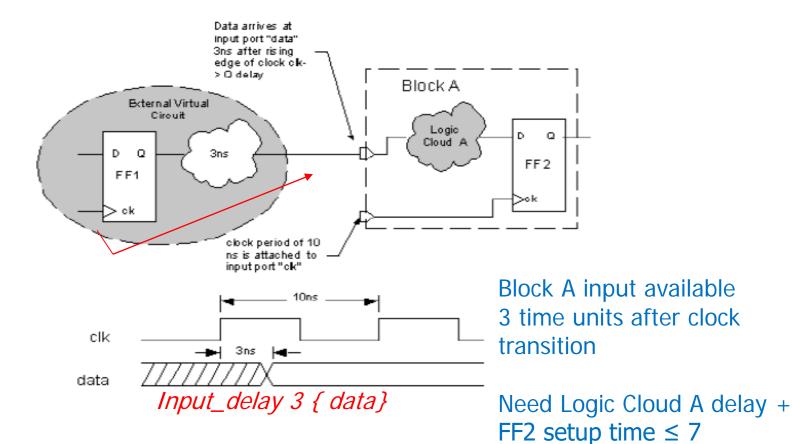
Input and output delays

- Delay from clock edge through "external" logic to an input port or internal pin.
 - set_input_delay 2.3 {in | in 2}
 - default input delay = 0
- Time a signal is required at output port by external destination before a clock edge
 - external circuit logic delay + external ff setup time
 - set_output_delay 7 —clock CLK I [all_outputs]
 - default output delay = 0



Input constraints

- Arrival time from <u>previous</u> ckt to input pin, relative to clock.
 - attribute: input_delay (default is 0)
 - command: set_input_delay 3 -clock clk dpin



Output constraints

Time from clock to valid output at pin, to be used by external ckt

attribute: output_delay

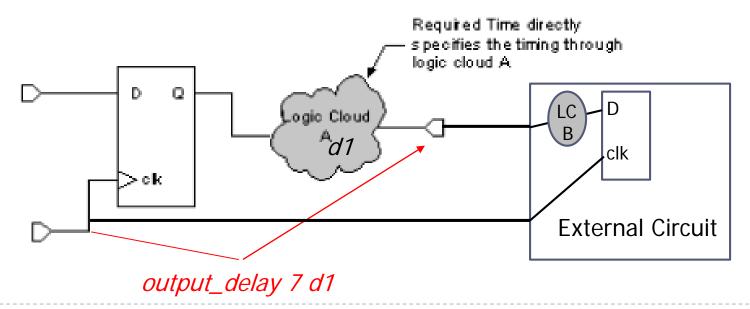
- command: set_output_delay 7 -clock CLK d1

Example: Clock cycle = 20

External ckt flip-flop setup time = 2

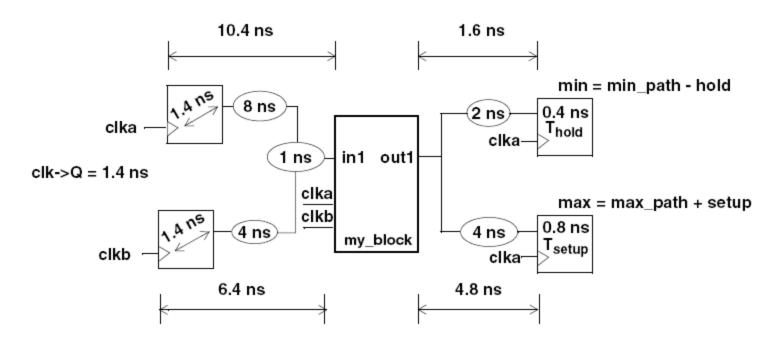
External ckt logic cloud (LC B) delay = 11

Output at d1 needed by 20 - (11 + 2) = 7





Sequential circuit example



create_clock -period 20 -waveform {5 15} clka create_clock -period 30 -waveform {10 25} clkb set_input_delay 10.4 -clock clka in1 set_input_delay 6.4 -clock clkb -add_delay in1 set_output_delay 1.6 -clock clka -min out1 set_output_delay 4.8 -clock clka -max out1

Required clock periods

Arrival at input pin from previous clock edge
Setup time of output pin from next clock edge



Path-based commands

- Path startpoint = input pin or register clock pin
- ▶ Path endpoint =output pin or register data pin
- Path constraint

```
set_max_delay -from from-list -to to-list value
```

- to/from-list = port, pin, clock or cell names
- If clock in *from-list*: all paths affected by that clock
- If clock in to-list: all related register data pins
- Register data pin: FFI or FFI/D
- Can specify —rise and/or —fall times
- Can add -through P to capture paths passing through P
- Can specify [all_outputs] or [all_inputs]



Path delay examples

Max delay requirements

- set_max_delay 10 -to out1 —from Reset
- set_max_delay 5.1 -from {ff1 ff2} -to {o1 o2}
- set_max_delay 3 —from busA[*] —to u I /Z
- set_max_delay 6 —to [all_outputs]
 - ▶ If no "from list", constrain paths from all start points
- set_max_delay 8 —from [all_inputs]
 - If no "to list", constrain paths to all end points
- Above also applies to: set_min_delay



Compiling the design

Compile (and optimize) the design

- compile –map_effort \$mapEffort I
 - design hierarchy preserved
 - map_effort = medium(default) or high
- compile –ungroup_all –map_effort \$mapEffort I
 - ▶ design "flattened" (ungrouped all levels collapsed)
- compile –incremental_mapping –map_effort \$mapEffort2
 - work on it some more incremental improvements

High-effort compile

- compile_ultra
- use on high-performance designs, tight time constraints
- specify -no_autoungroup to preserve hierarchy



Synthesis Output Files

- Design.v verilog structural netlist
 - change_names -rules verilog
 - write –format verilog –output file.v
- Design.sdf standard delay file for timing simulation
 - write_sdf -version 1.0 file.sdf
- Design.rep synthesis report (timing, area, etc)
 - redirect file.rep {report_timing}

More timing options on

redirect —append file.rep {report_area —hier } next slide.

- Design.ddc Synopsys database format (to view in DV)
 - write —format ddc —hierarchy -o file.ddc
- ▶ **Design.sdc** constraints for Encounter place/route
 - write_sdc file.sdc
- Design.pow power estimate
 - redirect file.pow { report_power }



Additional timing report options

report_timing

-to {list of signals}

-from {list of signals}

-through {list of pins}

-max_paths N

-loops {timing loops}

Inputs/flipflop outputs to these signals

Flip-flop outputs/inputs to these signals

Paths that go through these pins

Number of paths to report

Timing loops (comb. logic feedback)



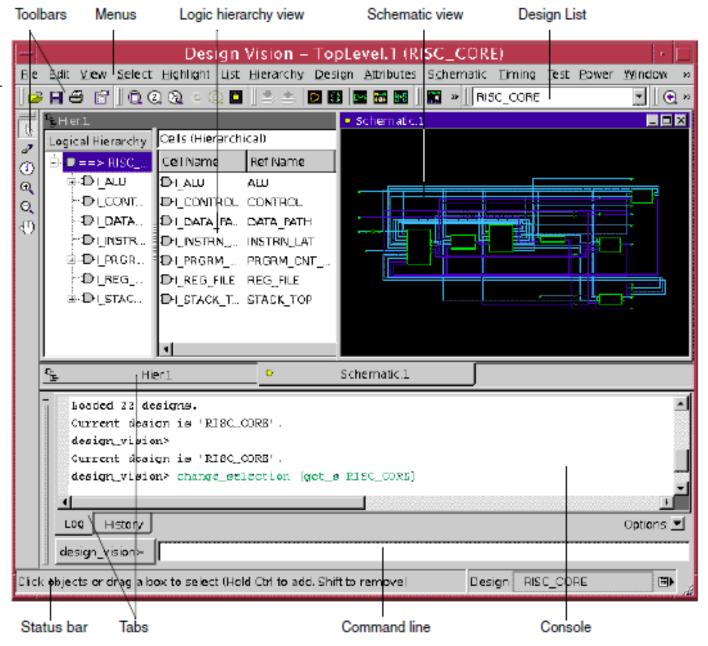
Balancing Loads

- Resolve load violations throughout the design
 - Fix loads after changing attributes, without rerunning optimize
 - Load balancing always done as part of optimize
 - ▶ Pays attention to OUTPUT_LOADS, OUTPUT_FANOUTS
- Mostly used at boundaries of hierarchical modules
 - Optimize balances loads within modules
- Command:

```
balance_loads [design-name] [-single]
```



DesignVision window



Modulo7 counter in DesignVision

